

Embedded Motion Control: Initial Design

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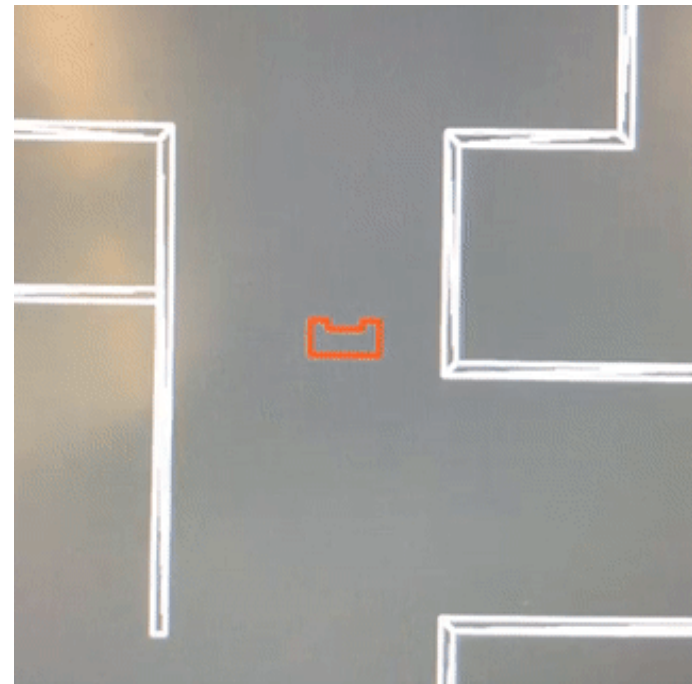
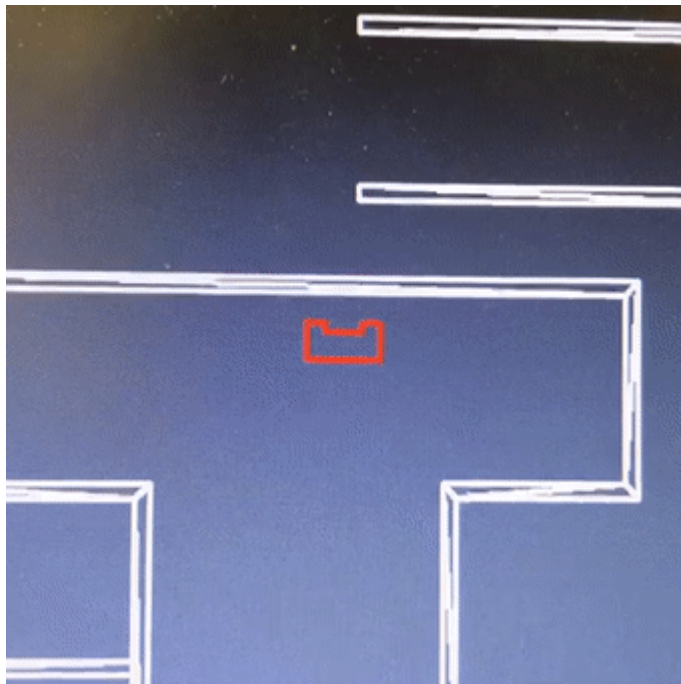
Tutor:

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What do we have? – What do we know? – What's next?

What do we have?

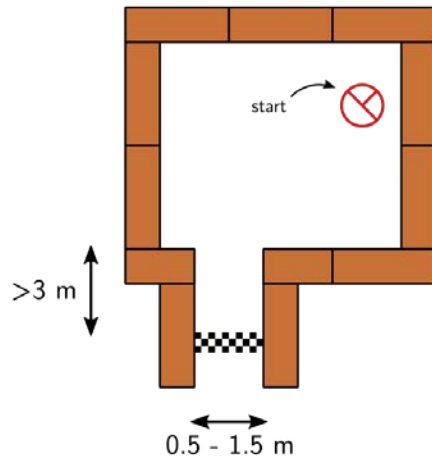
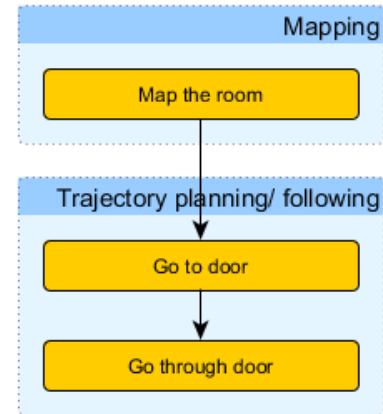


What do we have? – What do we know? – What's next?

What do we know?

Split it in three parts:

1. World model
2. Trajectory planning
3. Trajectory following

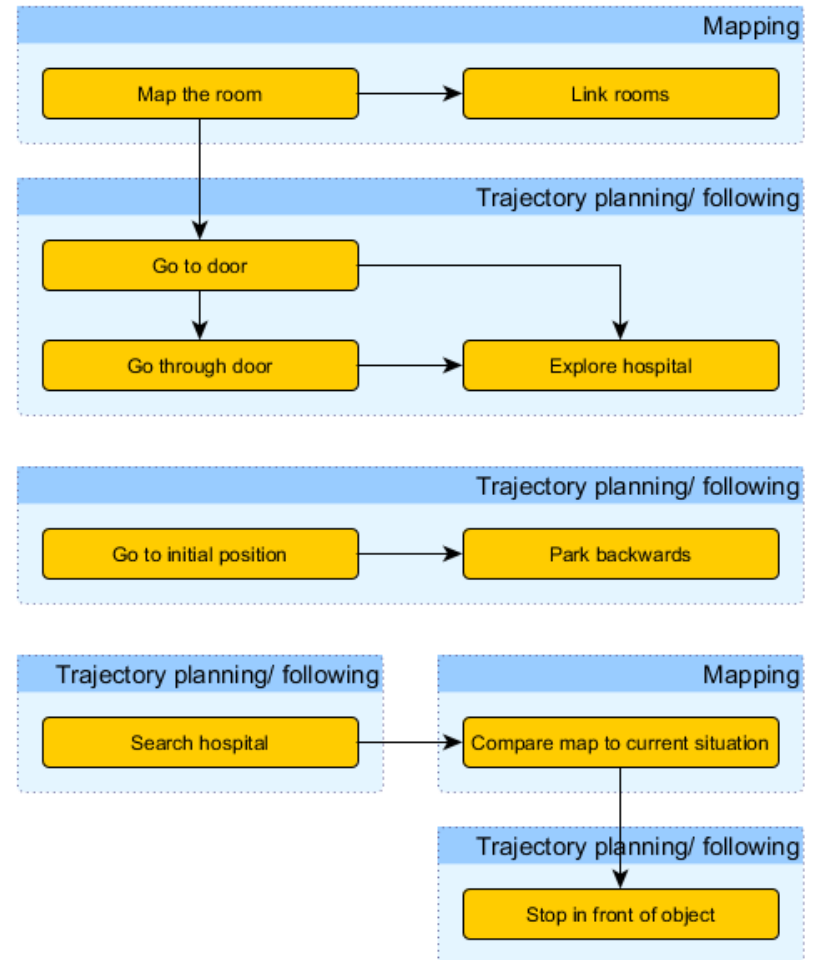
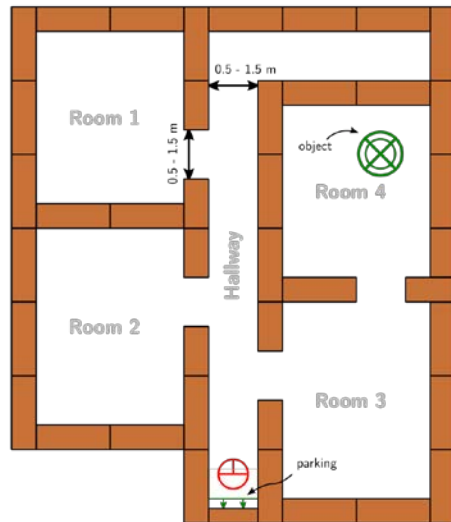


What do we have? – What do we know? – **What's next?**

What's next?

Split it in three parts:

1. World model
2. Trajectory planning
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Any questions?