

ID	Name	Description
0	DEMO	Minimal set of navigation data, this option is probably the most useful one, since it contains the values of all interesting parameters like: altitude, pitch, roll, yaw, battery level, fly state, control state.
1	TIME	Internal time of the drone.
2	Raw Measures	Raw sensor measurements
3	Phys Measures	Contains something about temperature measurements.
4	Gyros Offsets	
5	Euler Angles	
6	References	
7	TRIMS	Trim values.
8	RC_References	
9	PWM	Data about the motors, probably about the modulus of the Pulse Width Modulation signal.
10	Altitude	Multiple sensor data values about the drone's altitude.
11	Vision Raw	
12	Vision Of	
13	Vision	
14	Vision Perf	
15	Trackers Send	
16	Vision Detect	This option publishes the information about the detected tags if tag detection is enabled.
17	Watchdog	Watchdog status
18	ADC Data Frame	
19	Video Stream	
20	Games	
21	Pressure Raw	
22	Magneto	Contains fields that represent the sensor data from the magnetometer, which is basically the compass of the drone.
23	Wind Speed	
24	Kalman Pressure	
25	HDVideo Stream	
26	WIFI	
27	ZIMMU_3000	This option represents the GPS data
65536	CHECKSUM	The checksum option is always the last option of the packet, this option is 8 bytes long, where the first 4 bytes are the usual header and the next 4 bytes represent the 32-bits checksum.