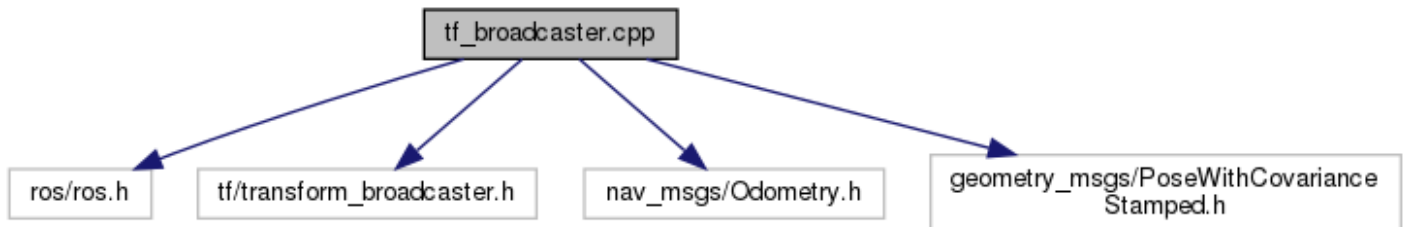


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tf_broadcaster.cpp File Reference

```
#include "ros/ros.h"
#include "tf/transform_broadcaster.h"
#include "nav_msgs/Odometry.h"
#include "geometry_msgs/PoseWithCovarianceStamped.h"
```

Include dependency graph for tf_broadcaster.cpp:



[Go to the source code of this file.](#)

Functions

```
void Callback (const nav_msgs::Odometry::ConstPtr &msg)
int main (int argc, char **argv)
```

Variables

```
geometry_msgs::TransformStamped odom_trans
```

Function Documentation

◆ Callback()

```
void Callback ( const nav_msgs::Odometry::ConstPtr & msg )
```

Definition at line **11** of file **tf_broadcaster.cpp**.

◆ main()

```
int main ( int    argc,  
          char ** argv  
          )
```

Definition at line [37](#) of file [tf_broadcaster.cpp](#).

Variable Documentation

◆ odom_trans

geometry_msgs::TransformStamped odom_trans

Definition at line [7](#) of file [tf_broadcaster.cpp](#).

[package_1](#)

Author(s):

autogenerated on Tue Jun 23 2020 13:49:16