

Embedded Motion Control

Group 2

Sil Schouten

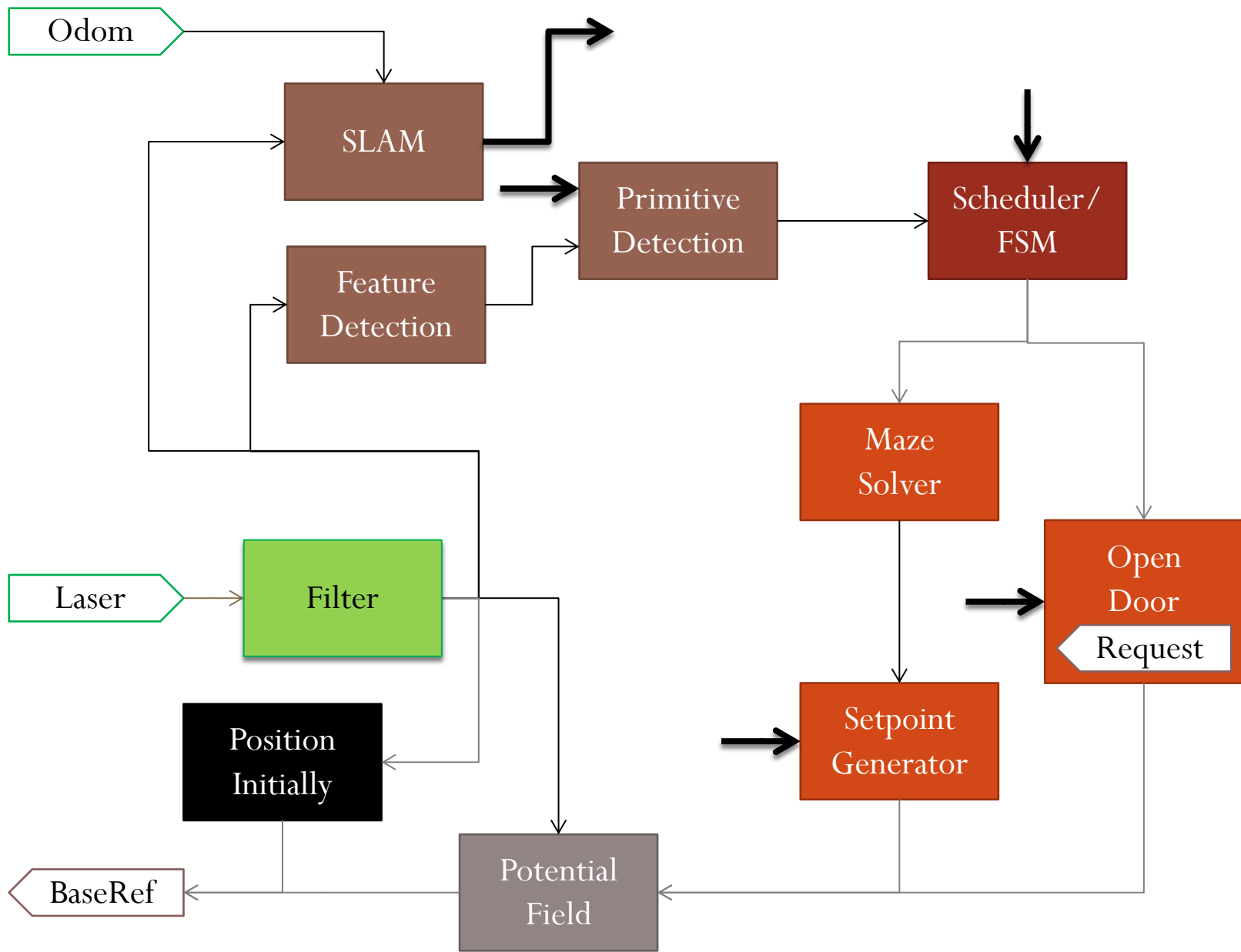
Daniël Pijnenborg

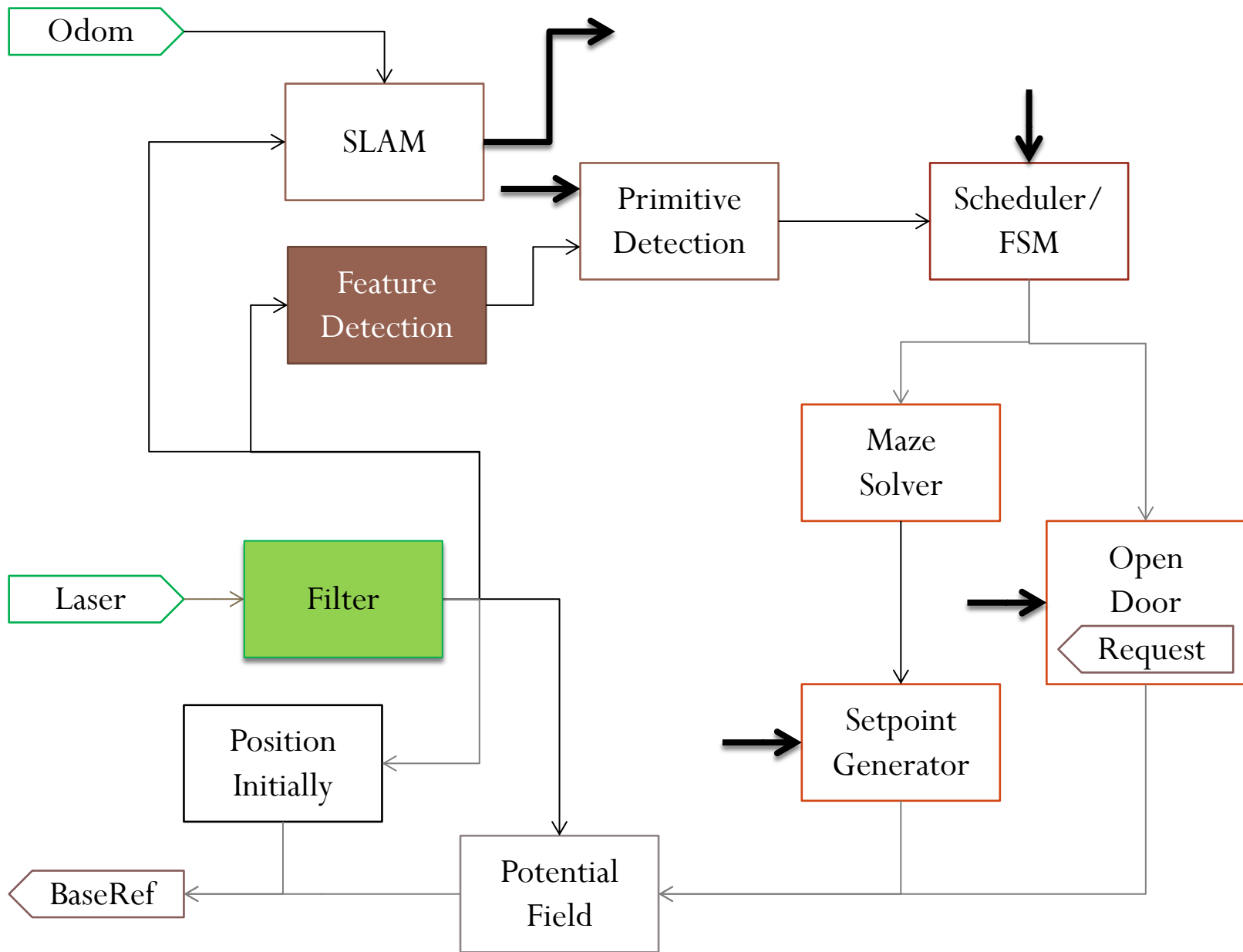
Rens Slenders

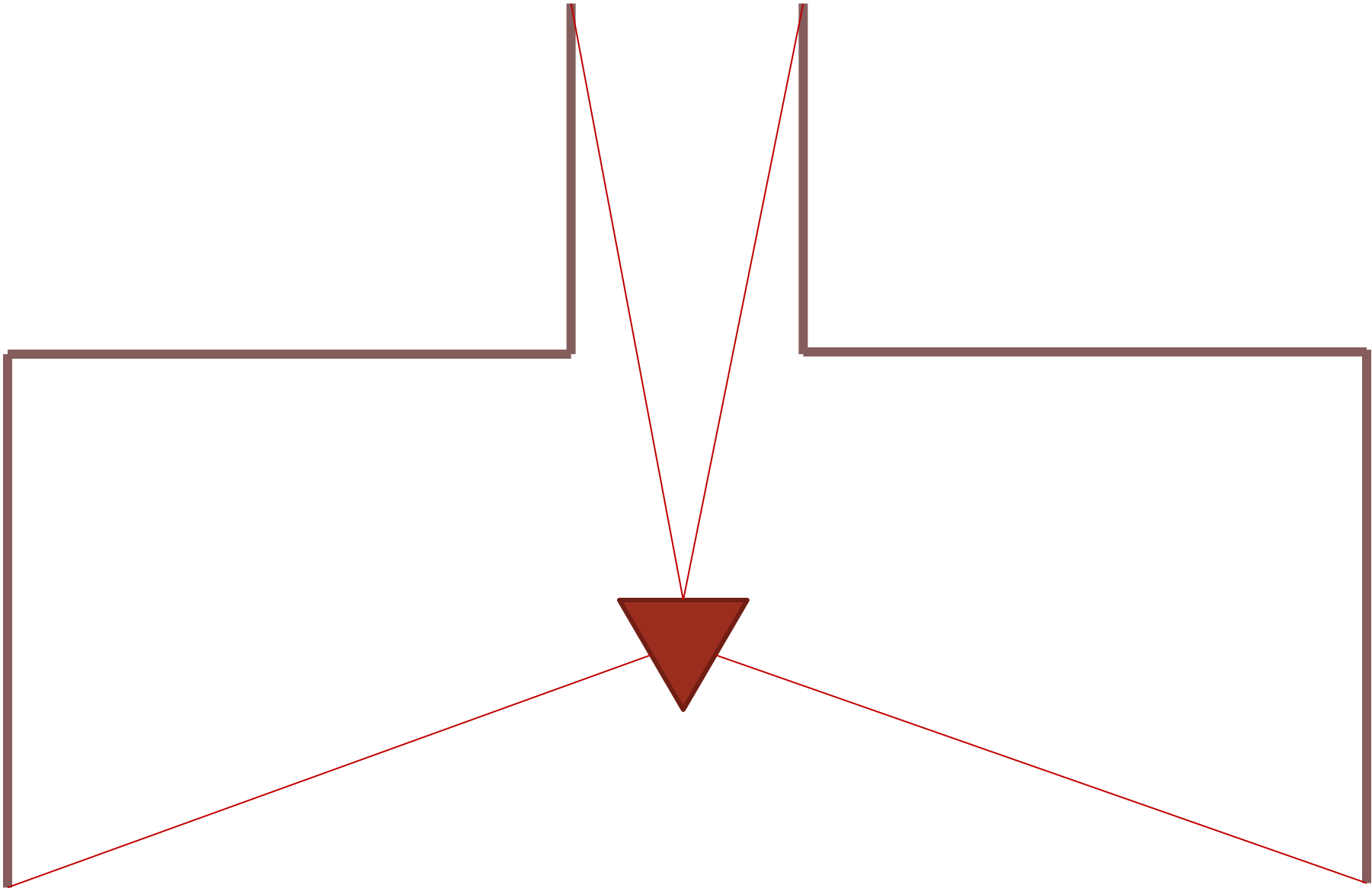
Joeri Roelofs

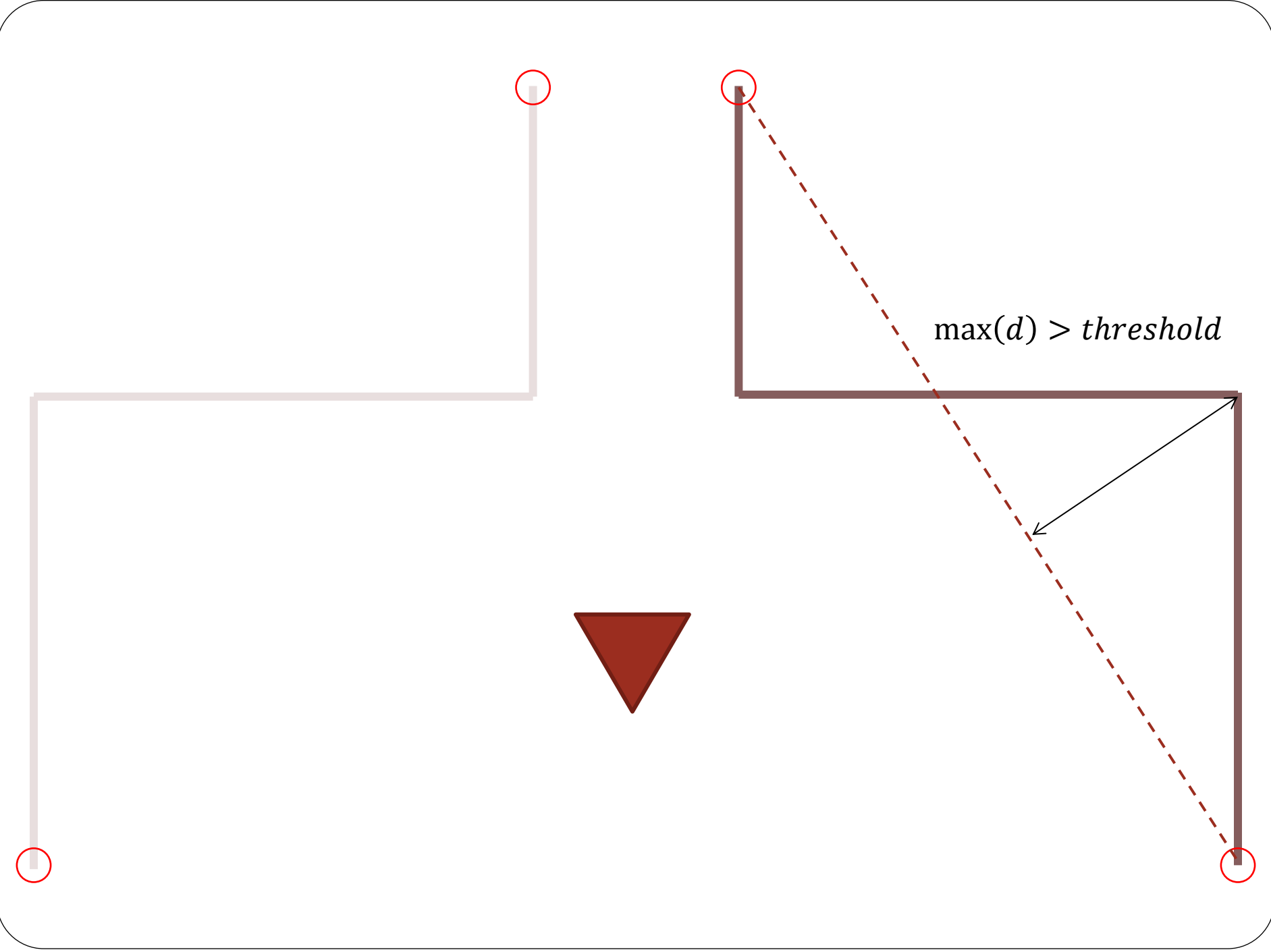
Matthijs van der Burgh

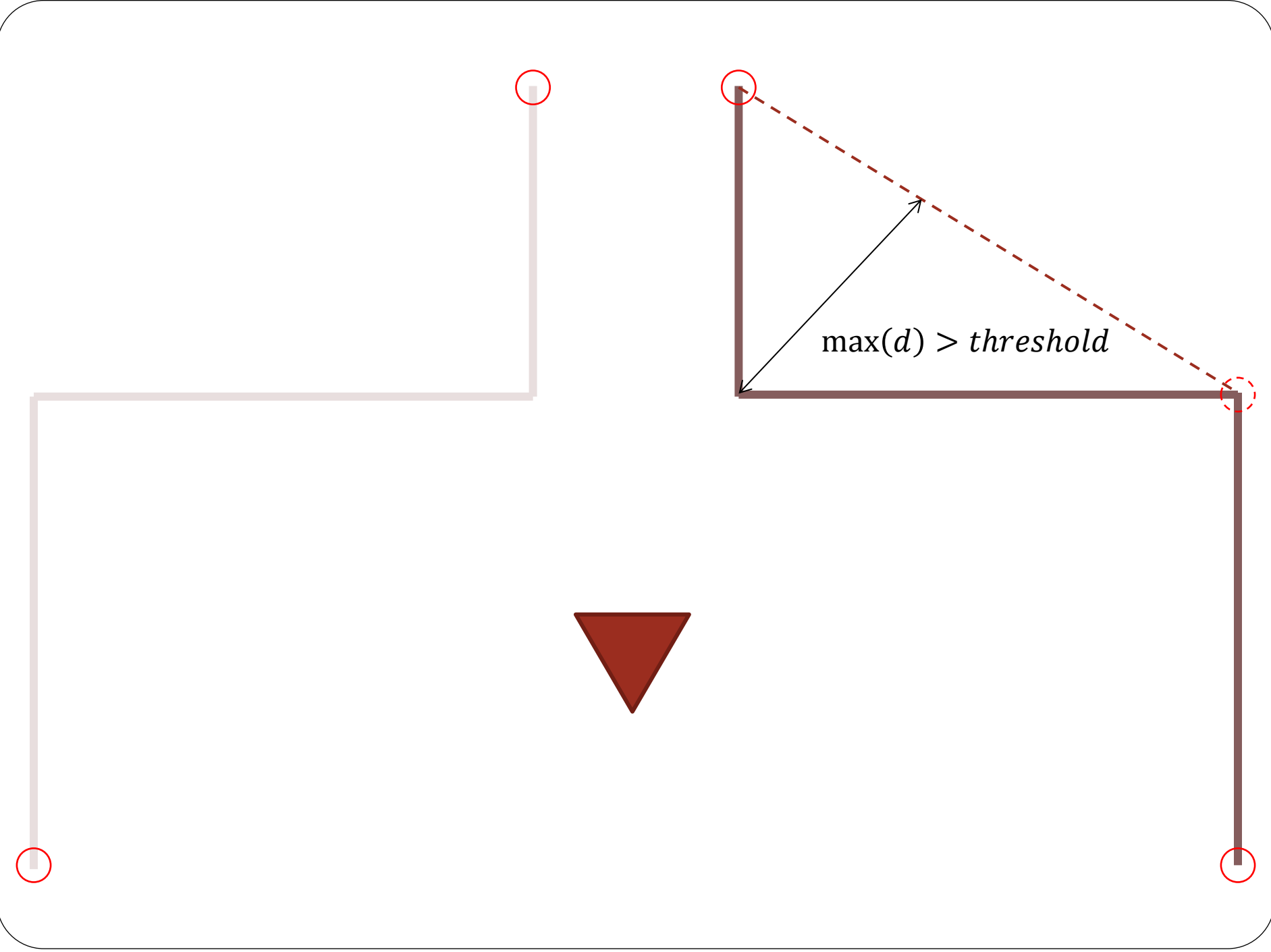
Joep Linssen

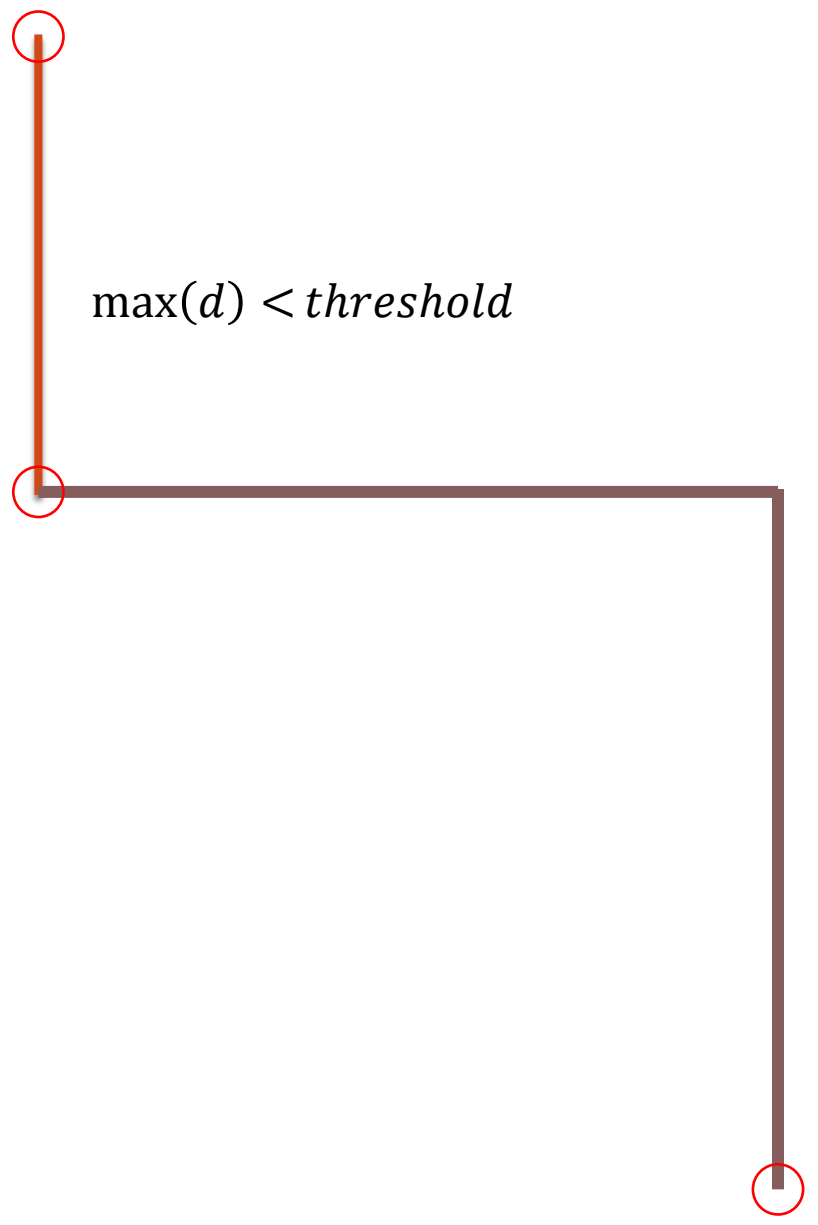




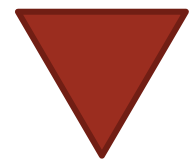


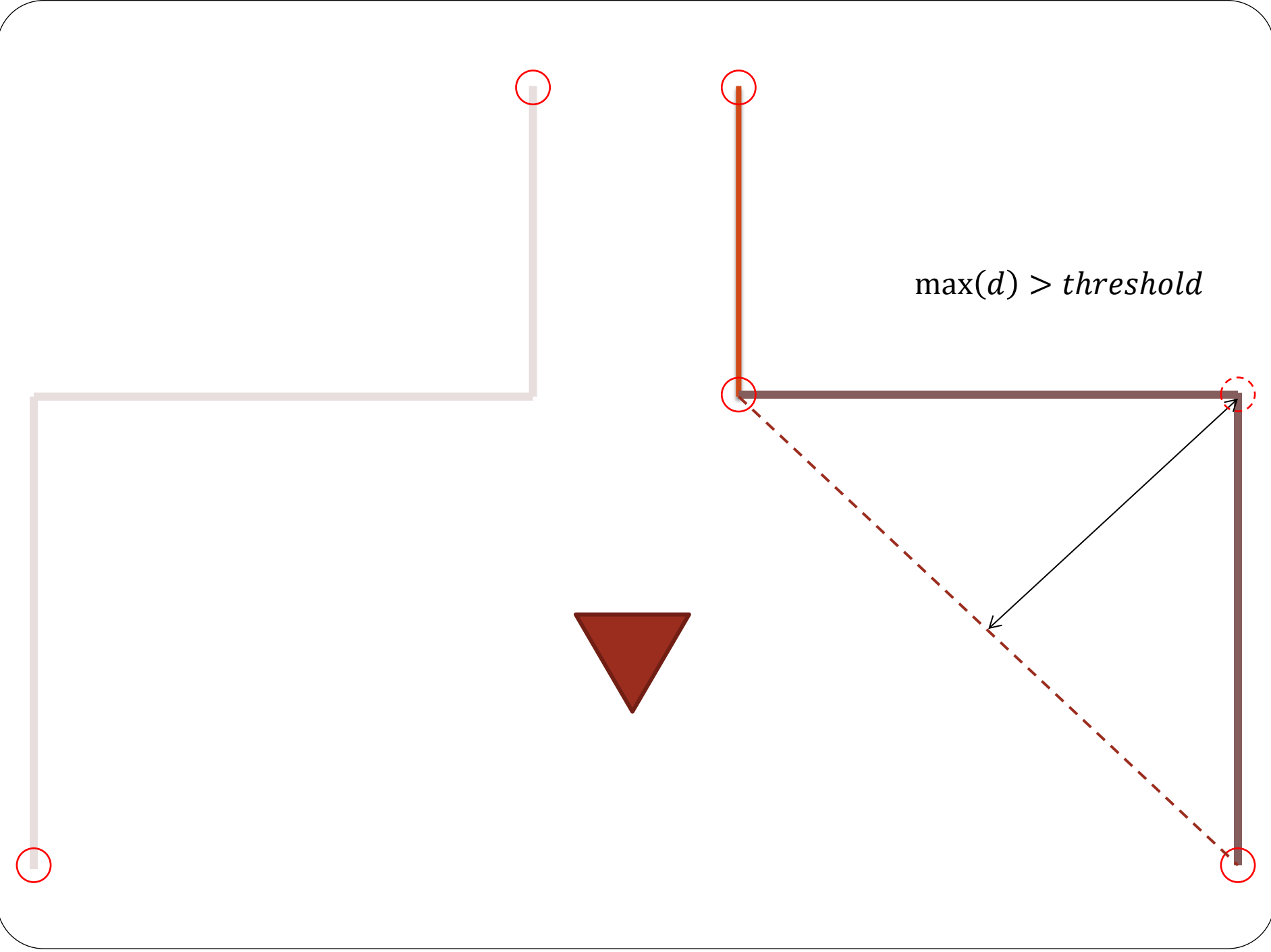




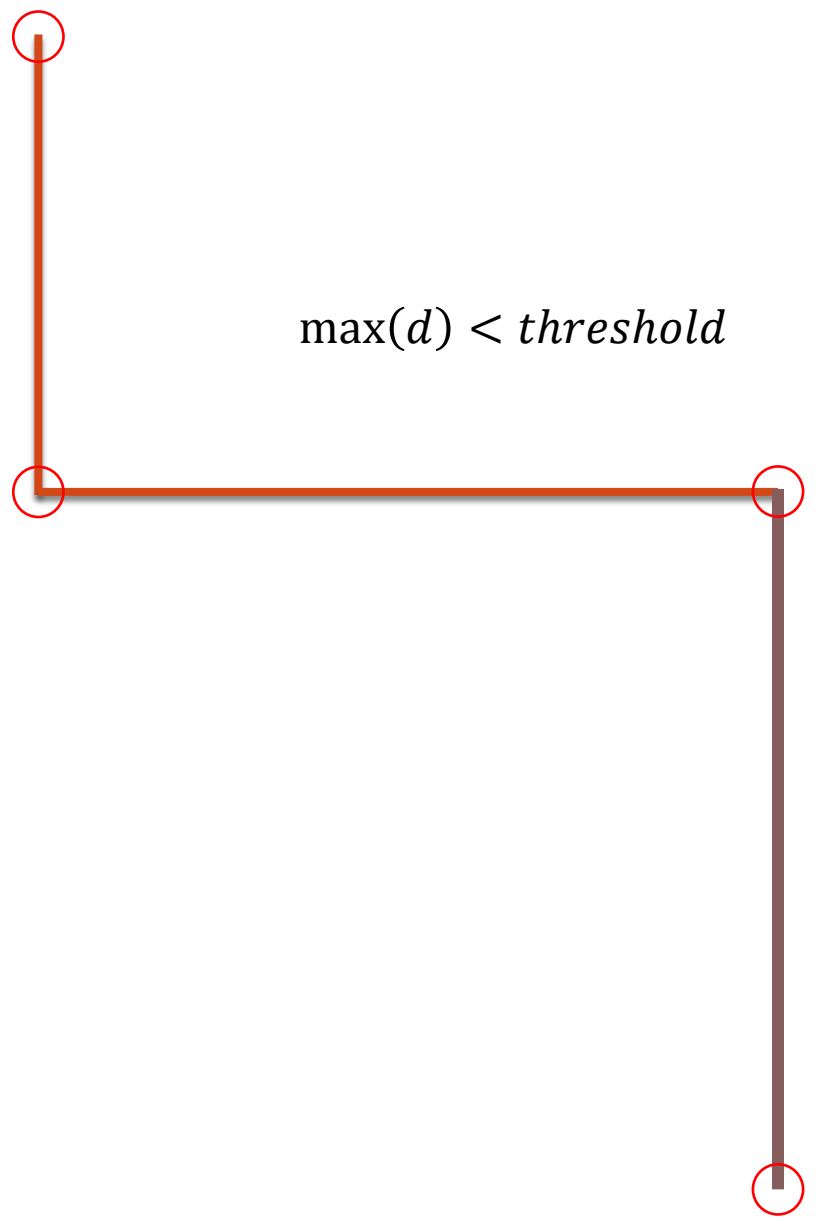


$\max(d) < threshold$

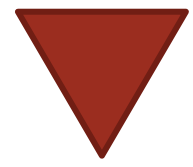


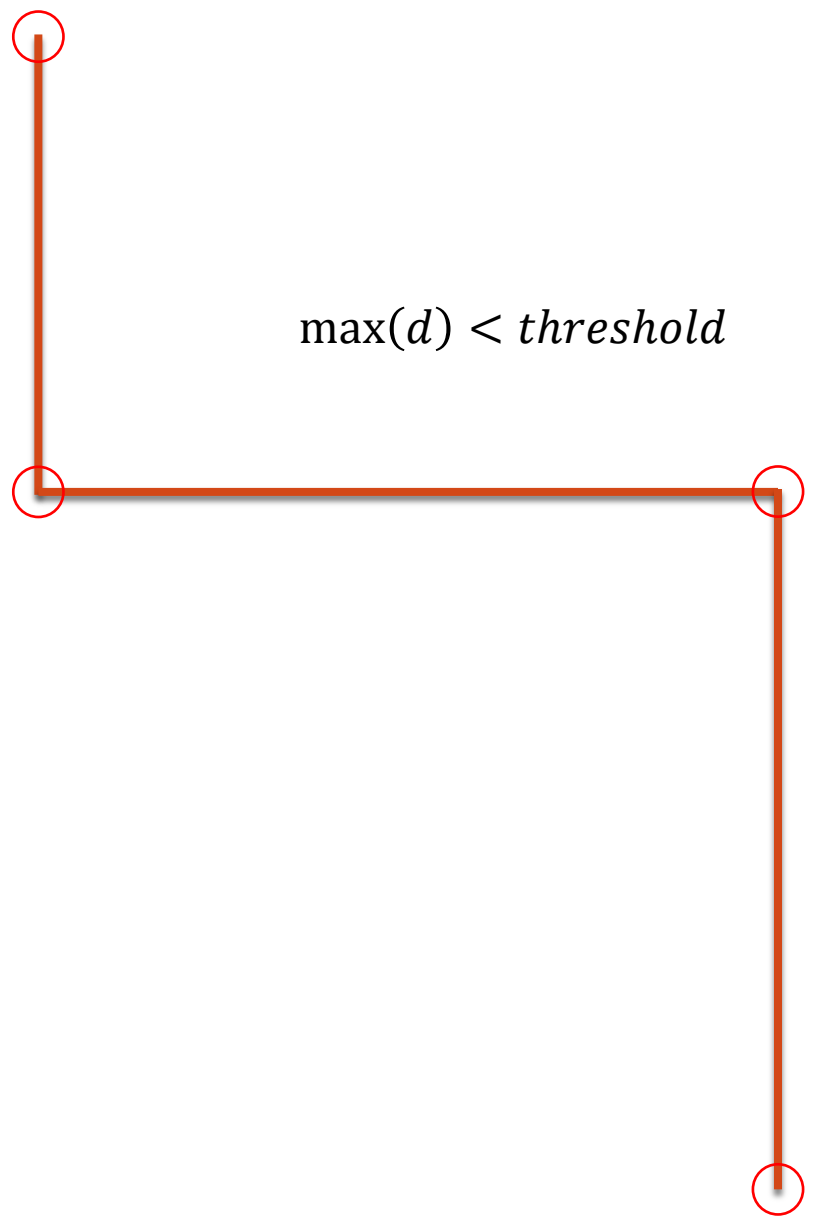


$\max(d) > \textit{threshold}$

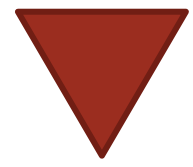


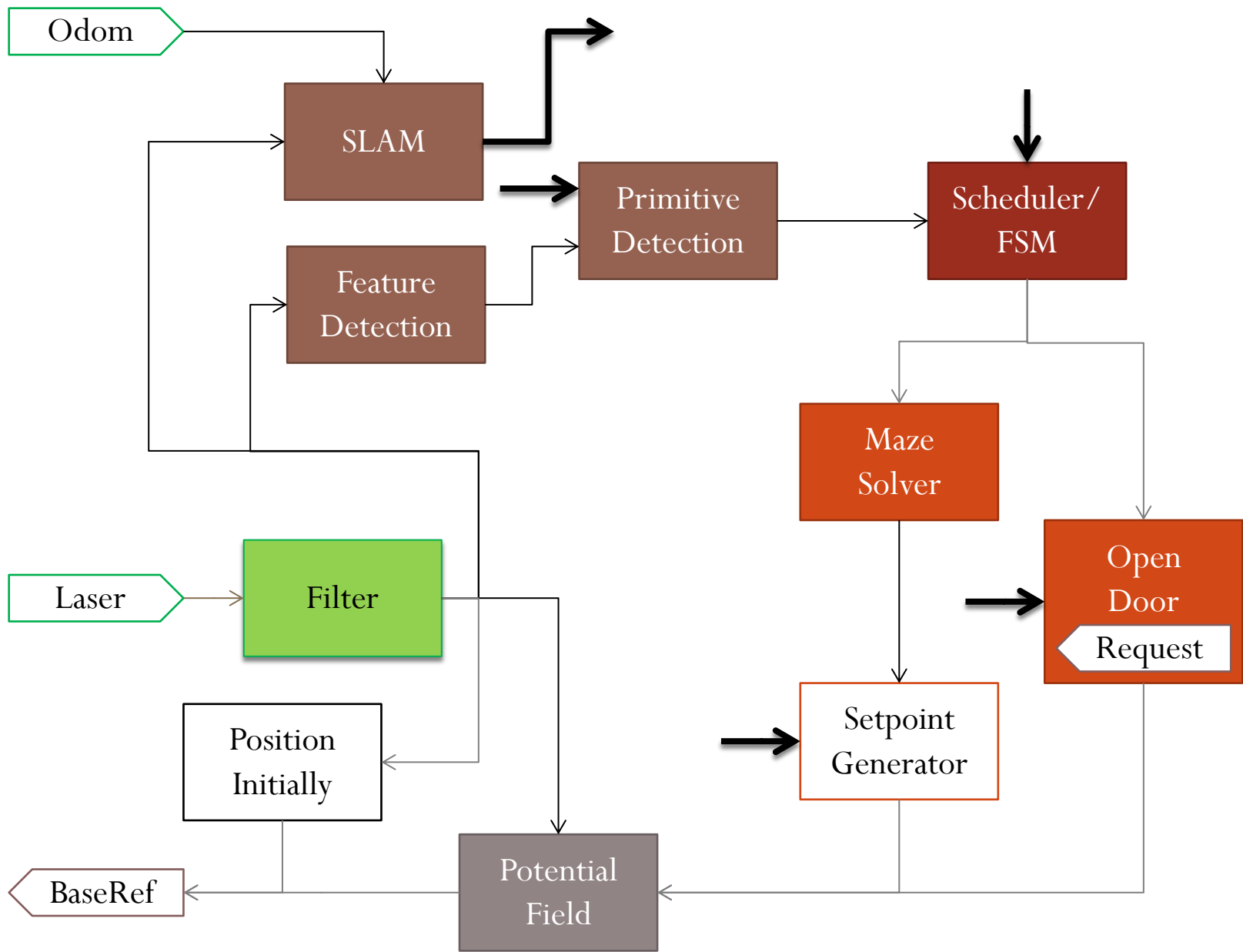
$\max(d) < \textit{threshold}$





$\max(d) < \textit{threshold}$





Video

Any Questions?